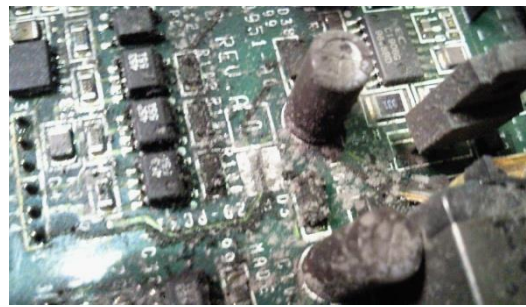
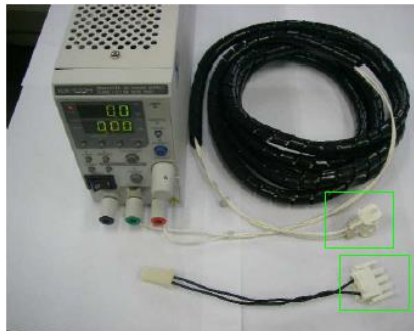
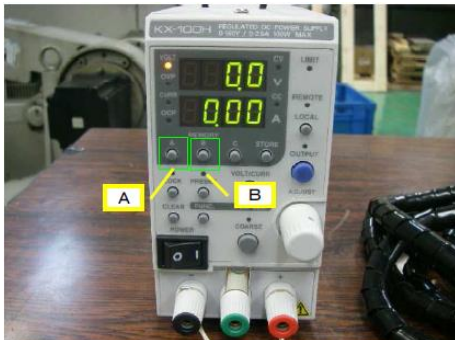


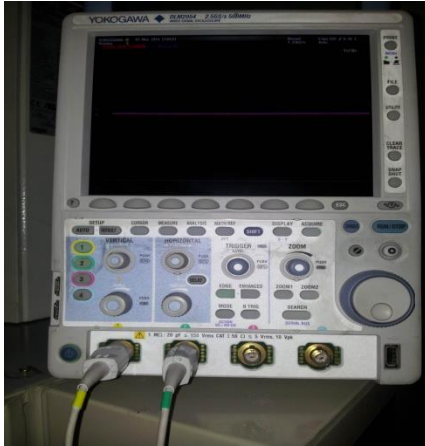
1) Controller diagnosis



2) Motor break check



3) Wave form check



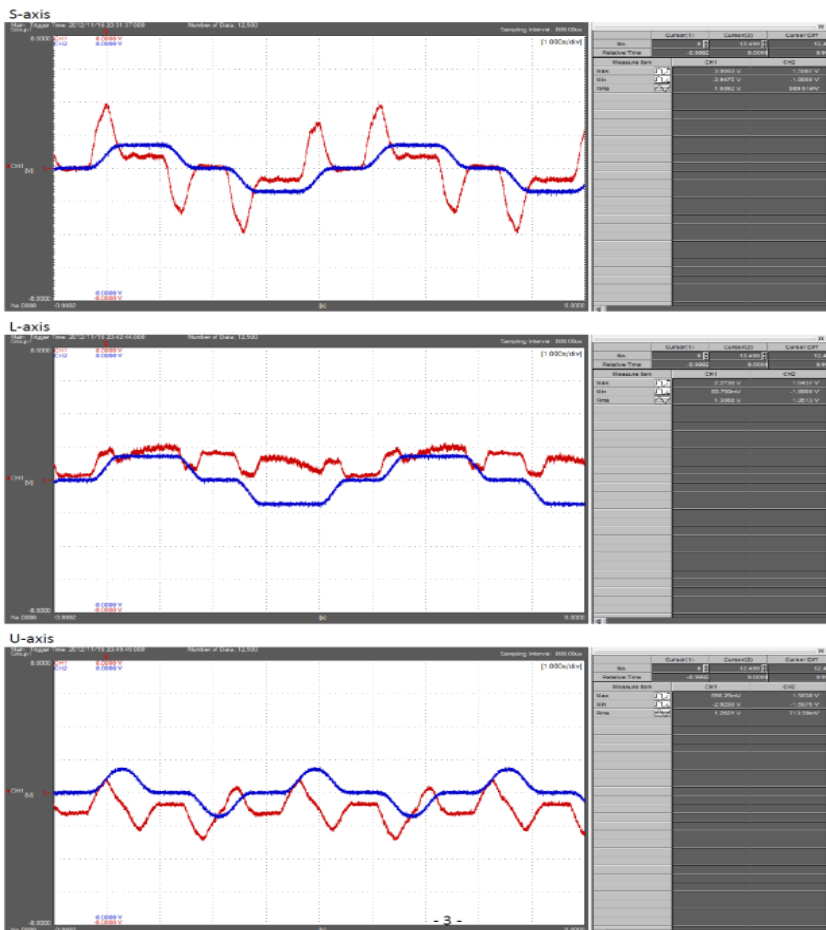
<Waveform measurement>



ROBOT No. : EPH4000-J10
Speed : 50%

Date : 16/11/2012
CH1: Torque monitor

CH2: Speed feedback



4)Steel dust check presence testing



5)Belt tension checking



6)Backlash check



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