
Troubleshooting

10.1 Alarm Displays	10-2
10.1.1 List of Alarms	10-2
10.1.2 Troubleshooting of Alarms	10-6
10.2 Warning Displays	10-20
10.2.1 List of Warnings	10-20
10.2.2 Troubleshooting of Warnings	10-21
10.3 Troubleshooting Malfunction Based on Operation and Conditions of the Servomotor	10-24

10.1 Alarm Displays

The following sections describe troubleshooting in response to alarm displays.

The alarm name, alarm meaning, alarm stopping method, alarm code output, and alarm reset capability are listed in order of the alarm numbers in *10.1.1 List of Alarms*.

The causes of alarms and troubleshooting methods are provided in *10.1.2 Troubleshooting of Alarms*.

10.1.1 List of Alarms

This section provides list of alarms.

■ Servomotor Stopping Method

If an alarm occurs, the servomotor can be stopped by doing either of the following operations.

Gr.1: The servomotor is stopped according to the setting in Pn001.0 if an alarm occurs. Pn001.0 is factory-set to stop the servomotor by applying the DB.

Gr.2: The servomotor is stopped according to the setting in Pn00B.1 if an alarm occurs. Pn00B.1 is factory-set to stop the servomotor by setting the speed reference to "0." The servomotor under torque control will always use the Gr.1 method to stop. By setting Pn00B.1 to 1, the servomotor stops using the same method as Gr.1. When coordinating a number of servomotors, use this stopping method to prevent machine damage that may result due to differences in the stop method.

■ Alarm Reset

Available: Removing the cause of alarm and then executing the alarm reset can clear the alarm.

N/A: Executing the alarm reset cannot clear the alarm.

Alarm Number	Alarm Name	Meaning	Servomotor Stopping Method	Alarm Reset	Alarm Code Output		
					ALO1	ALO2	ALO3
A.020	Parameter Checksum Error 1	The data of the parameter in the SERVOPACK is incorrect.	Gr.1	N/A	H	H	H
A.021	Parameter Format Error 1	The data of the parameter in the SERVOPACK is incorrect.	Gr.1	N/A			
A.022	System Checksum Error 1	The data of the parameter in the SERVOPACK is incorrect.	Gr.1	N/A			
A.030	Main Circuit Detector Error	Detection data for main circuit is incorrect.	Gr.1	Available			
A.040	Parameter Setting Error 1	The parameter setting is outside the setting range.	Gr.1	N/A			
A.041	Encoder Output Pulse Setting Error	The encoder output pulse (Pn212) is outside the setting range or does not satisfy the setting conditions.	Gr.1	N/A			
A.042	Parameter Combination Error	Combination of some parameters exceeds the setting range.	Gr.1	N/A			
A.044	Semi-closed/Fully-closed Loop Control Parameter Setting Error	The settings of the option module and Pn00B.3, Pn002.3 do not match.	Gr.1	N/A			
A.050	Combination Error	The SERVOPACK and the servomotor capacities do not match each other.	Gr.1	Available			
A.051	Unsupported Device Alarm	The device unsupported was connected.	Gr.1	N/A			
A.0b0	Cancelled Servo ON Command Alarm	The servo ON signal (/S-ON) was sent from the host controller after executing a utility function that turns ON servomotor.	Gr.1	Available	L	H	H
A.100	Overcurrent or Heat Sink Overheated	An overcurrent flowed through the IGBT or the heat sink of the SERVOPACK was overheated.	Gr.1	N/A			

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Alarm Number	Alarm Name	Meaning	Servo-motor Stopping Method	Alarm Reset	Alarm Code Output		
					ALO1	ALO2	ALO3
A.300	Regeneration Error	Regenerative circuit or regenerative resistor is faulty.	Gr.1	Available	L	L	H
A.320	Regenerative Overload	Regenerative energy exceeds regenerative resistor capacity.	Gr.2	Available			
A.330	Main Circuit Power Supply Wiring Error	<ul style="list-style-type: none"> Setting of AC input/DC input is incorrect. Power supply wiring is incorrect. 	Gr.1	Available			
A.400	Overvoltage	Main circuit DC voltage is excessively high.	Gr.1	Available	H	H	L
A.410	Undervoltage	Main circuit DC voltage is excessively low.	Gr.2	Available			
A.450	Main-Circuit Capacitor Overvoltage	The capacitor of the main circuit has deteriorated or is faulty.	Gr.1	N/A	L	H	L
A.510	Overspeed	The servomotor speed is above the maximum rotational speed.	Gr.1	Available			
A.511	Overspeed of Encoder Output Pulse Rate	The pulse output speed upper limit of the set encoder output pulse (Pn212) is exceeded.	Gr.1	Available			
A.520	Vibration Alarm	Incorrect vibration at the motor speed was detected.	Gr.1	Available			
A.521	Autotuning Alarm	Vibration was detected while performing tuning-less function.	Gr.1	Available			
A.710	Overload: High Load	The servomotor was operating for several seconds to several tens of seconds under a torque largely exceeding ratings.	Gr.2	Available	L	L	L
A.720	Overload: Low Load	The servomotor was operating continuously under a torque exceeding ratings.	Gr.1	Available			
A.730 A.731	Dynamic Brake Overload	When the dynamic brake was applied, rotational energy exceeded the capacity of dynamic brake resistor.	Gr.1	Available			
A.740	Overload of Surge Current Limit Resistor	The main circuit power was frequently turned ON and OFF.	Gr.1	Available			
A.7A0	Heat Sink Overheated	The heat sink of the SERVOPACK exceeded 100°C.	Gr.2	Available			
A.7AB	Built-in Fan in SERVOPACK Stopped	The fan inside the SERVOPACK stopped.	Gr.1	Available			
A.810	Encoder Backup Error	The power supplies to the encoder all failed and position data was lost.	Gr.1	N/A			
A.820	Encoder Checksum Error	The checksum results of encoder memory is incorrect.	Gr.1	N/A			
A.830	Absolute Encoder Battery Error	The battery voltage was lower than the specified value after the control power supply was turned ON.	Gr.1	Available			
A.840	Encoder Data Error	Data in the encoder is incorrect.	Gr.1	N/A			
A.850	Encoder Overspeed	The encoder was rotating at high speed when the power was turned ON.	Gr.1	N/A			
A.860	Encoder Overheated	The internal temperature of encoder is too high.	Gr.1	N/A			
A.8A0	External Encoder Error	External encoder is faulty.	Gr.1	Available			
A.8A1	External Encoder Error of Module	Serial converter unit is faulty.	Gr.1	Available			
A.8A2	External Encoder Error of Sensor	External encoder is faulty.	Gr.1	Available			

(cont'd)

Alarm Number	Alarm Name	Meaning	Servo-motor Stopping Method	Alarm Reset	Alarm Code Output		
					ALO1	ALO2	ALO3
A.8A3	External Encoder Error of Position	The position data of external encoder is faulty.	Gr.1	Available			
A.8A5	External Encoder Overspeed	The overspeed from the external encoder occurred.	Gr.1	Available	H	H	H
A.8A6	External Encoder Overheated	The overheat from the external encoder occurred.	Gr.1	Available			
A.A□□*1	SERVOPACK: Command Option Module Alarms	–	–	–	–	–	–
A.b10	Speed Reference A/D Error	The A/D converter for speed reference input is faulty.	Gr.2	Available			
A.b11	Speed Reference A/D Data Error	A/D conversion data of speed reference input is incorrect.	Gr.2	Available			
A.b20	Reference Torque Input Read Error	The A/D converter for torque reference input is faulty.	Gr.2	Available			
A.b31	Current Detection Error 1	The current detection circuit for phase U is faulty.	Gr.1	N/A			
A.b32	Current Detection Error 2	The current detection circuit for phase V is faulty.	Gr.1	N/A			
A.b33	Current Detection Error 3	The detection circuit for the current is faulty.	Gr.1	N/A	H	H	H
A.bF0	System Alarm 0	"Internal program error 0" of the SERVO-PACK occurred.	Gr.1	N/A			
A.bF1	System Alarm 1	"Internal program error 1" of the SERVO-PACK occurred.	Gr.1	N/A			
A.bF2	System Alarm 2	"Internal program error 2" of the SERVO-PACK occurred.	Gr.1	N/A			
A.bF3	System Alarm 3	"Internal program error 3" of the SERVO-PACK occurred.	Gr.1	N/A			
A.bF4	System Alarm 4	"Internal program error 4" of the SERVO-PACK occurred.	Gr.1	N/A			
A.C10	Servo Overrun Detected	The servomotor ran out of control.	Gr.1	Available			
A.C80	Absolute Encoder Clear Error and Multiturn Limit Setting Error	The multiturn for the absolute encoder was not properly cleared or set.	Gr.1	N/A			
A.C90	Encoder Communications Error	Communications between the SERVO-PACK and the encoder is not possible.	Gr.1	N/A			
A.C91	Encoder Communications Position Data Error	An encoder position data calculation error occurred.	Gr.1	N/A			
A.C92	Encoder Communications Timer Error	An error occurs in the communications timer between the encoder and the SERVO-PACK.	Gr.1	N/A			
A.CA0	Encoder Parameter Error	Encoder parameters are faulty.	Gr.1	N/A	L	H	L
A.Cb0	Encoder Echoback Error	Contents of communications with encoder are incorrect.	Gr.1	N/A			
A.CC0	Multiturn Limit Disagreement	Different multiturn limits have been set in the encoder and the SERVO-PACK.	Gr.1	N/A			
A.CF1	Feedback Option Module Communications Error (Reception error)	Reception from the Feedback Option Module is faulty.	Gr.1	N/A			
A.CF2	Feedback Option Module Communications Error (Timer stop)	Timer for communications with the Feedback Option Module is faulty.	Gr.1	N/A			

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Alarm Number	Alarm Name	Meaning	Servo-motor Stopping Method	Alarm Reset	Alarm Code Output		
					ALO1	ALO2	ALO3
A.d00	Position Error Overflow	Position error exceeded the value of excessive position error alarm level (Pn520) when the servomotor power is ON.	Gr.1	Available	L	L	H
A.d01	Position Error Overflow Alarm at Servo ON	This alarm occurs if the servomotor power is turned ON when the position error is greater than the set value of Pn526 while the servomotor power is OFF.	Gr.1	Available			
A.d02	Position Error Overflow Alarm by Speed Limit at Servo ON	When the position errors remain in the error counter, Pn529 limits the speed if the servomotor power is turned ON. If Pn529 limits the speed in such a state, this alarm occurs when reference pulses are input and the number of position errors exceeds the value set for the excessive position error alarm level (Pn520).	Gr.2	Available			
A.d10	Motor-load Position Error Overflow	During fully-closed loop control, the position error between motor and load is excessive.	Gr.2	Available			
A.E71	Safety Option Module Detection Failure	Detection of the safety option module failed.	Gr.1	N/A	H	L	L
A.E72	Feedback Option Module Detection Failure	Detection of the Feedback Option Module failed.	Gr.1	N/A			
A.E74	Unsupported Safety Option Module	An unsupported safety option module was connected.	Gr.1	N/A			
A.E75	Unsupported Feedback Option Module	An unsupported feedback option module was connected.	Gr.1	N/A			
A.E81 ^{*2}	SERVOPACK: Safety Module Alarm	–	–	–	–	–	–
A.Eb1	Safety Function Signal Input Timing Error	The safety function signal input timing is faulty.	Gr.1	N/A	H	L	L
A.Eb□ ^{*2}	SERVOPACK: Safety Module Alarms	–	–	–	–	–	–
A.EC□ ^{*2}	SERVOPACK: Safety Module Alarms	–	–	–	–	–	–
A.F10	Main Circuit Cable Open Phase	With the main power supply ON, voltage was low for more than 1 second in phase R, S, or T.	Gr.2	Available	H	L	H
FL-1 ^{*3}	System Alarm	Internal program error occurred in the SERVOPACK	–	N/A	Undefined		
FL-2 ^{*3}			–	N/A			
CPF00	Digital Operator Transmission Error 1	Digital operator (JUSP-OP05A-1-E) fails to communicate with the SERVOPACK (e.g., CPU error).	–	N/A	Undefined		
CPF01	Digital Operator Transmission Error 2		–	N/A			
A.--	Not an error	Normal operation status	–	–	H	H	H

- *1. These alarms occur in SERVOPACKs with command option modules. For details, refer to the manual for the command option module that is connected.
- *2. These alarms occur in SERVOPACKs with safety modules. For details, refer to *Σ-V Series User's Manual, Safety Module* (No.: SIEP C720829 06).
- *3. These alarms are not stored in the alarm history and are displayed only in the panel display.

10.1.2 Troubleshooting of Alarms

If an error occurs in servo drives, an alarm display such as A.□□□ and CPF□□ will appear on the panel operator.

Refer to the following table to identify the cause of an alarm and the action to be taken.

Contact your Yaskawa representative if the problem cannot be solved by the described corrective action.

Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.020: Parameter Checksum Error 1 (The parameter data in the SERVOPACK is incorrect.)	The power supply voltage suddenly dropped.	Measure the power supply voltage.	Set the power supply voltage within the specified range, and set Fn005 to initialize the parameter.
	The power supply went OFF while changing a parameter setting.	Check the circumstances when the power supply went OFF.	Set Fn005 to initialize the parameter and then set the parameter again.
	The number of times that parameters were written exceeded the limit.	Check to see if the parameters were frequently changed through the host controller.	The SERVOPACK may be faulty. Replace the SERVOPACK. Reconsider the method of writing parameters.
	Malfunction caused by noise from the AC power supply or grounding line, static electricity noise, etc.	Turn the power supply ON and OFF several times. If the alarm still occurs, there may be noise interference.	Take countermeasures against noise.
	Gas, water drops, or cutting oil entered the SERVOPACK and caused failure of the internal components.	Check the installation conditions.	The SERVOPACK may be faulty. Replace the SERVOPACK.
	A SERVOPACK fault occurred.	Turn the power supply ON and OFF several times. If the alarm still occurs, the SERVOPACK may be faulty.	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.021: Parameter Format Error 1 (The parameter data in the SERVOPACK is incorrect.)	The software version of SERVOPACK that caused the alarm is older than that of the written parameter.	Check Fn012 to see if the set software version agrees with that of the SERVOPACK. If not, an alarm may occur.	Write the parameter of another SERVOPACK of the same model with the same software version. Then turn the power OFF and then ON again.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.022: System Checksum Error 1 (The parameter data in the SERVOPACK is incorrect.)	The power supply voltage suddenly dropped.	Measure the power supply voltage.	The SERVOPACK may be faulty. Replace the SERVOPACK.
	The power supply went OFF while setting an utility function.	Check the circumstances when the power supply went OFF.	The SERVOPACK may be faulty. Replace the SERVOPACK.
	A SERVOPACK fault occurred.	Turn the power supply ON and OFF several times. If the alarm still occurs, the SERVOPACK may be faulty.	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.030: Main Circuit Detector Error	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.040: Parameter Setting Error 1 (The parameter setting was out of the setting range.)	The SERVOPACK and servomotor capacities do not match each other.	Check the combination of SERVOPACK and servomotor capacities.	Select the proper combination of SERVOPACK and servomotor capacities.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
	The parameter setting is out of the setting range.	Check the setting ranges of the parameters that have been changed.	Set the parameter to a value within the setting range.
	The electronic gear ratio is out of the setting range.	Check the electronic gear ratio. The ratio must satisfy: $0.001 < (Pn20E/Pn210) < 4000$.	Set the electronic gear ratio in the range: $0.001 < (Pn20E/Pn210) < 4000$.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.041: Encoder Output Pulse Setting Error	The encoder output pulse (Pn212) is out of the setting range and does not satisfy the setting conditions.	Check the parameter Pn212.	Set Pn212 to a correct value.
A.042:*1 Parameter Combination Error	The speed of program JOG operation (Fn004) is lower than the setting range after having changed the electronic gear ratio (Pn20E/Pn210) or the servomotor.	Check if the detection conditions*1 are satisfied.	Decrease the setting of the electronic gear ratio (Pn20E/Pn210).
	The speed of program JOG operation (Fn004) is lower than the setting range after having changed the setting of the program JOG movement speed (Pn533).	Check if the detection conditions*1 are satisfied.	Increase the setting of the program JOG movement speed (Pn533).
	The moving speed of advanced autotuning is lower than the setting range after having changed the electronic gear ratio (Pn20E/Pn210) or the servomotor.	Check if the detection conditions*1 are satisfied.	Decrease the setting of the electronic gear ratio (Pn20E/Pn210).
A.044: Semi-closed/Fully- closed Loop Control Parameter Setting Error	The setting of the fully-closed module does not match with that of Pn002.3.	Check the settings of Pn002.3.	The setting of fully-closed module must be compatible with the setting of Pn002.3.
A.050: Combination Error (The SERVOPACK and servomotor capacities do not correspond.)	The SERVOPACK and servomotor capacities do not match each other.	Check the capacities to see if they satisfy the following condition: $\frac{1}{4} \leq \frac{\text{Servomotor capacity}}{\text{SERVOPACK capacity}} \leq 4$	Select the proper combination of SERVOPACK and servomotor capacities.
	An encoder fault occurred.	Replace the servomotor and see if the alarm occurs again.	Replace the servomotor (encoder).
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.051: Unsupported Device Alarm	An unsupported serial converter unit, encoder, or external encoder is connected to the SERVOPACK.	Check the product specifications, and select the correct model.	Select the correct combination of units.
A.0b0: Cancelled Servo ON Command Alarm	After executing the utility function to turn ON the power to the motor, the servo ON signal (/S-ON) was sent from the host controller.	–	Turn the SERVOPACK power supply OFF and then ON again or execute a software reset.

*1. Detection conditions

If one of the following conditions detected, an alarm occurs.

- $\text{Pn533} [\text{min}^{-1}] \times \frac{\text{Encoder resolution}}{6 \times 10^5} \leq \frac{\text{Pn20E}}{\text{Pn210}}$
- $\text{Max Motor Speed} [\text{min}^{-1}] \times \frac{\text{Encoder resolution}}{\text{About } 3.66 \times 10^{12}} \geq \frac{\text{Pn20E}}{\text{Pn210}}$

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.100: Overcurrent or Heat Sink Overheated (An overcurrent flowed through the IGBT or heat sink of SERVO- PACK overheated.)	Incorrect wiring or contact fault of main circuit cables.	Check the wiring. Refer to <i>3.1 Main Circuit Wiring</i> .	Correct the wiring.
	Short-circuit or ground fault of main circuit cables.	Check for short-circuits across the servomotor terminal phases U, V, and W, or between the grounding and servomotor terminal phases U, V, or W. Refer to <i>3.1 Main Circuit Wiring</i> .	The cable may be short-circuited. Replace the cable.
	Short-circuit or ground fault inside the servomotor.	Check for short-circuits across the servomotor terminal phases U, V, and W, or between the grounding and servomotor terminal phases U, V, or W. Refer to <i>3.1 Main Circuit Wiring</i> .	The servomotor may be faulty. Replace the servomotor.
	Short-circuit or ground fault inside the SERVOPACK.	Check for short-circuits across the servomotor connection terminals U, V, and W on the SERVOPACK, or between the grounding and terminal U, V, or W. Refer to <i>3.1 Main Circuit Wiring</i> .	The SERVOPACK may be faulty. Replace the SERVOPACK.
	Incorrect wiring or contact fault of the regenerative resistor.	Check the wiring. Refer to <i>3.6 Connecting Regenerative Resistors</i> .	Correct the wiring.
	The dynamic brake (DB: Emergency stop executed from the SERVOPACK) was frequently activated, or the DB overload alarm occurred.	Check the power consumed by DB resistance (Un00B) to see how many times the DB has been used. Or, check the alarm history display Fn000 to see if the DB overload alarm A.730 or A.731 was reported.	Change the SERVOPACK model, operating conditions, or the mechanism so that the DB does not need to be used so frequently.
	The generated regenerative resistor value exceeded the SERVOPACK regenerative energy processing capacity.	Check the regenerative load ratio (Un00A) to see how many times the regenerative resistor has been used.	Check the operating condition including overload, and reconsider the regenerative resistor value.
	The SERVOPACK regenerative resistance is too small.	Check the regenerative load ratio (Un00A) to see how many times the regenerative resistor has been used.	Change the regenerative resistance value to a value larger than the SERVOPACK minimum allowable resistance value.
	A heavy load was applied while the servomotor was stopped or running at a low speed.	Check to see if the operating conditions are outside servo drive specifications.	Reduce the load applied to the servomotor or increase the operating speed.
	Malfunction caused by noise interference.	Improve the wiring or installation environment, such as by reducing noise, and check to see if the alarm recurs.	Take countermeasures for noise, such as correct wiring of the FG. Use an FG wire size equivalent to the SERVOPACK main circuit wire size.
A SERVOPACK fault occurred.	–	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.	

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.300: Regeneration Error	<ul style="list-style-type: none"> Regenerative resistor capacity (Pn600) is set to a value other than 0 for a SGDVR70, -R90, -1R6, -2R1, or -2R8 SERVO-PACK, and an external regenerative resistor is not connected. An external regenerative resistor is not connected to the SGDVR470, SGDVR550, SGDVR590, SGDVR780, SGDVR210, SGDVR260, SGDVR280, or SGDVR370 SERVOPACK. 	Check the external regenerative resistor connection and the value of the Pn600.	Connect the external regenerative resistor, or set Pn600 to 0 if no regenerative resistor is required.
	The jumper between the power supply terminals B2 and B3 is removed for the SERVOPACKs other than the SERVOPACKs shown above.	Confirm that a jumper is mounted between the power supply terminals B2 and B3.	Correctly mount a jumper.
	The external regenerative resistor is incorrectly wired, or is removed or disconnected.	Check the external regenerative resistor connection.	Correctly connect the external regenerative resistor.
	A SERVOPACK fault occurred.	–	While the main circuit power supply is OFF, turn the control power supply OFF and then ON again. If the alarm still occurs, the SERVO-PACK may be faulty. Replace the SERVOPACK.
A.320: Regenerative Overload	The power supply voltage exceeds the specified limit.	Measure the power supply voltage.	Set the power supply voltage within the specified range.
	Insufficient external regenerative resistance, regenerative resistor capacity, or SERVOPACK capacity. Or, regenerative power has been continuously flowing back.	Check the operating condition or the capacity using the capacity selection Software SigmaJunma-Size+, etc.	Change the regenerative resistance, regenerative resistor capacity, or SERVOPACK capacity. Reconsider the operating conditions using the capacity selection software SigmaJunmaSize+, etc.
	Regenerative power continuously flowed back because negative load was continuously applied.	Check the load applied to the servomotor during operation.	Reconsider the system including servo, machine, and operating conditions.
	The setting of parameter Pn600 is smaller than the external regenerative resistor's capacity.	Check the external regenerative resistor connection and the value of the Pn600.	Set the Pn600 to a correct value.
	The external regenerative resistance is too high.	Check the regenerative resistance.	Change the regenerative resistance to a correct value or use an external regenerative resistor of appropriate capacity.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.330: Main Circuit Power Supply Wiring Error (Detected when the power to the main circuit is turned ON.)	The regenerative resistor disconnected when the SERVOPACK power supply voltage was high.	Measure the resistance of the regenerative resistor using a measuring instrument.	When using a regenerative resistor built in the SERVOPACK: Replace the SERVOPACK. When using an external regenerative resistor: Replace the external regenerative resistor.
	In the AC power input mode, DC power was supplied.	Check the power supply to see if it is a DC power supply.	Correct the settings to match the actual power supply specifications.
	In the DC power input mode, AC power was supplied.	Check the power supply to see if it is an AC power supply.	Correct the settings to match the actual power supply specifications.
	Regenerative resistor capacity (Pn600) is set to a value other than 0 for a SGD7-R70, -R90, -1R6, -2R1, or -2R8 SERVOPACK, and an external regenerative resistor is not connected.	Check the external regenerative resistor connection and the value of the Pn600.	Connect the external regenerative resistor, or set Pn600 to 0 if no regenerative resistor is required.
	The jumper between the power supply terminals B2 and B3 is removed for the SERVOPACKs other than the SERVOPACKs shown above.	Confirm that a jumper is mounted between the power supply terminals B2 and B3.	Correctly mount a jumper.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.400: Overvoltage (Detected in the SER- VOPACK main circuit power supply section.)	<ul style="list-style-type: none"> For 100-VAC SERVOPACKs: The AC power supply voltage exceeded 145 V. For 200-VAC SERVOPACKs: The AC power supply voltage exceeded 290 V. For 400-VAC SERVOPACKs: The AC power supply voltage exceeded 580 V. For 200-VAC SERVOPACKs: with DC power supply input: The DC power supply voltage exceeded 410 V. For 400-VAC SERVOPACKs: The DC power supply voltage exceeded 820 V. 	Measure the power supply voltage.	Set AC/DC power supply voltage within the specified range.
	The power supply is unstable, or was influenced by a lightning surge.	Measure the power supply voltage.	Improve the power supply conditions by installing a surge absorber, etc. Then, turn the power supply OFF and ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
	Voltage for AC power supply was too high during acceleration or deceleration.	Check the power supply voltage and the speed and torque during operation.	Set AC power supply voltage within the specified range.
	The external regenerative resistance is too high for the actual operating conditions.	Check the operating conditions and the regenerative resistance.	Select a regenerative resistance value appropriate for the operating conditions and load.
	The moment of inertia ratio exceeded the allowable value.	Confirm that the moment of inertia ratio is within the allowable range.	Increase the deceleration time, or reduce the load.
	A SERVOPACK fault occurred.	—	Turn the control power OFF and then ON again while the main circuit power supply is OFF. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.410: Undervoltage (Detected in the SERVOPACK main circuit power supply section.)	<ul style="list-style-type: none"> For 100-VAC SERVOPACKs: The AC power supply voltage is 49 V or less. For 200-VAC SERVOPACKs: The AC power supply voltage is 120 V or less. For 400-VAC SERVOPACKs: The AC power supply voltage is 240 V or less. 	Measure the power supply voltage.	Set the power supply voltage within the specified range.
	The power supply voltage dropped during operation.	Measure the power supply voltage.	Increase the power supply capacity.
	Occurrence of instantaneous power interruption.	Measure the power supply voltage.	When the instantaneous power cut hold time (Pn509) is set, decrease the setting.
	The SERVOPACK fuse is blown out.	—	Replace the SERVOPACK, connect a reactor, and run the SERVOPACK.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.450: Main-Circuit Capacitor Overvoltage	A SERVOPACK fault occurred.	—	Replace the SERVOPACK.
A.510: Overspeed (The servomotor speed exceeds the maximum.)	The order of phases U, V, and W in the servomotor wiring is incorrect.	Check the motor wiring.	Confirm that the servomotor is correctly wired.
	A reference value exceeding the overspeed detection level was input.	Check the input value.	Reduce the reference value or adjust the gain.
	The motor speed exceeded the maximum.	Check the motor speed waveform.	Reduce the speed reference input gain, adjust the servo gain, or reconsider the operating conditions.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.511: Overspeed of Encoder Output Pulse Rate	The encoder output pulse frequency exceeded the limit.	Check the encoder output pulse setting.	Decrease the setting of the encoder output pulse (Pn212).
	The encoder output pulse output frequency exceeded the limit because the motor speed was too high.	Check the encoder output pulse output setting and motor speed.	Decrease the motor speed.
A.520: Vibration Alarm	Abnormal vibration was detected at the motor speed.	Check for abnormal noise from the servomotor, and check the speed and torque waveforms during operation.	Reduce the motor speed or reduce the speed loop gain (Pn100).
	The moment of inertia ratio (Pn103) value is greater than the actual value or is greatly changed.	Check the moment of inertia ratio.	Set the moment of inertia ratio (Pn103) to an appropriate value.
A.521: Autotuning Alarm (Vibration was detected while executing the one-parameter tuning, EasyFFT, or tuning-less function.)	The servomotor vibrated considerably while performing tuning-less function.	Check the motor speed waveform.	Reduce the load so that the moment of inertia ratio falls within the allowable value, or raise the load level using the tuning-less levels setting (Fn200) or reduce the rigidity level.
	The servomotor vibrated considerably during one-parameter tuning or EasyFFT.	Check the motor speed waveform.	Check the operation procedure of corresponding function and take a corrective action.

(cont'd)

Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.710: A.720: Overload A.710: High Load A.720: Low Load	Incorrect wiring or contact fault of servomotor and encoder.	Check the wiring.	Confirm that the servomotor and encoder are correctly wired.
	Operation beyond the overload protection characteristics.	Check the servomotor overload characteristics and executed run command.	Reconsider the load conditions and operating conditions. Or, increase the motor capacity.
	Excessive load was applied during operation because the servomotor was not driven due to mechanical problems.	Check the executed operation reference and motor speed.	Remove the mechanical problems.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.730: A.731: Dynamic Brake Overload (An excessive power consumption of dynamic brake was detected.)	The servomotor rotates because of external force.	Check the operation status.	Take measures to ensure the servomotor will not rotate because of external force.
	The rotating energy at a DB stop exceeds the DB resistance capacity.	Check the power consumed by DB resistance (Un00B) to see how many times the DB has been used.	Reconsider the following: <ul style="list-style-type: none"> • Reduce the motor reference speed. • Reduce the moment of inertia ratio. • Reduce the number of times of the DB stop operation.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.740: Overload of Surge Current Limit Resistor (The main circuit power is turned ON/OFF too frequently.)	The inrush current limit resistor operation frequency at the main circuit power supply ON/OFF operation exceeds the allowable range.	–	Reduce the frequency of turning the main circuit power supply ON/OFF.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.7A0: Heat Sink Overheated (Detected when the heat sink temperature exceeds 100°C.)	The surrounding air temperature is too high.	Check the surrounding air temperature using a thermostat.	Decrease the surrounding air temperature by improving the SERVOPACK installation conditions.
	The overload alarm has been reset by turning OFF the power too many times.	Check the alarm history display (Fn000) to see if the overload alarm was reported.	Change the method for resetting the alarm.
	Excessive load or operation beyond the regenerative energy processing capacity.	Check the accumulated load ratio (Un009) to see the load during operation, and the regenerative load ratio (Un00A) to see the regenerative energy processing capacity.	Reconsider the load and operating conditions.
	Incorrect SERVOPACK installation orientation or/and insufficient space around the SERVOPACK.	Check the SERVOPACK installation conditions.	Install the SERVOPACK correctly as specified.
	A SERVOPACK fault occurred.	–	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.7AB: Built-in Fan in SERVOPACK Stopped	The fan inside the SERVOPACK stopped.	Check for foreign matter or debris inside the SERVOPACK.	Remove foreign matter or debris from the SERVOPACK. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

(cont'd)

Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.810: Encoder Backup Error (Only when an absolute encoder is connected.) (Detected on the encoder side.)	Alarm occurred when the power to the absolute encoder was initially turned ON.	Check to see if the power was turned ON initially.	Set up the encoder (Fn008).
	The encoder cable disconnected, and connected again.	Check to see if the power was turned ON initially.	Confirm the connection and set up the encoder (Fn008).
	The power from both the control power supply (+5 V) from the SERVOPACK and the battery power supply is not being supplied.	Check the encoder connector battery or the connector contact status.	Replace the battery or take similar measures to supply power to the encoder, and set up the encoder (Fn008).
	An absolute encoder fault occurred.	—	If the alarm cannot be reset by setting up the encoder again, replace the servomotor.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.820: Encoder Checksum Error (Detected on the encoder side.)	An encoder fault occurred.	—	<ul style="list-style-type: none"> Absolute encoder Set up the encoder again using Fn008. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor. Absolute encoder that shows values for a single rotation or incremental encoder The servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.830: Absolute Encoder Battery Error (The absolute encoder battery voltage is lower than the specified value.)	The battery connection is incorrect.	Check the battery connection.	Reconnect the battery.
	The battery voltage is lower than the specified value 2.7 V.	Measure the battery voltage.	Replace the battery.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.840: Encoder Data Error (Detected on the encoder side.)	An encoder malfunctioned.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	Malfunction of encoder because of noise interference, etc.	—	Correct the wiring around the encoder by separating the encoder cable from the servomotor main circuit cable or by checking the grounding and other wiring.
A.850: Encoder Overspeed (Detected when the control power supply was turned ON.) (Detected on the encoder side.)	The servomotor speed is higher than 200 min ⁻¹ when the control power supply was turned ON.	Check the motor rotating speed (Un000) to confirm the servomotor speed when the power is turned ON.	Reduce the servomotor speed to a value less than 200 min ⁻¹ , and turn ON the control power supply.
	An encoder fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

(cont'd)

Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.860: Encoder Overheated (Only when an absolute encoder is connected.) (Detected on the encoder side.)	The ambient operating temperature around the servomotor is too high.	Measure the ambient operating temperature around the servomotor.	The ambient operating temperature must be 40°C or less.
	The motor load is greater than the rated load.	Check the accumulated load ratio (Un009) to see the load.	The motor load must be within the specified range.
	An encoder fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.8A0: External Encoder Error	Setting the zero point position of external absolute encoder failed because the servomotor rotated.	Before setting the zero point position, use the fully-closed feedback pulse counter (Un00E) to confirm that the servomotor is not rotating.	The servomotor must be stopped while setting the zero point position.
	An external encoder fault occurred.	—	Replace the external encoder.
A.8A1: External Encoder Error of Module	An external encoder fault occurred.	—	Replace the external encoder.
	A serial converter unit fault occurred.	—	Replace the serial converter unit.
A.8A2: External Encoder Error of Sensor (Incremental)	An external encoder fault occurred.	—	Replace the external encoder.
A.8A3: External Encoder Error of Position (Absolute)	An external absolute encoder fault occurred.	—	The external absolute encoder may be faulty. Refer to the encoder manufacturer's instruction manual for corrective actions.
A.8A5: External Encoder Overspeed	The overspeed from the external encoder occurred.	Check the maximum speed of the external encoder.	Keep the external encoder below its maximum speed.
A.8A6: External Encoder Overheated	The overheat from the external encoder occurred.	—	Replace the external encoder.
	A malfunction occurred in the speed reference input section.	—	Clear and reset the alarm and restart the operation.
A.b10: Speed Reference A/D Error (Detected when the servo is ON.)	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
	A malfunction occurred in the speed reference input section.	—	Clear and reset the alarm and restart the operation.
A.b11: Speed Reference A/D Data Error	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
	A malfunction occurred in the reading section of the torque reference input.	—	Clear and reset the alarm and restart the operation.
A.b20: Reference Torque Input Read Error (Detected when the servo is ON.)	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
	A malfunction occurred in the reading section of the torque reference input.	—	Clear and reset the alarm and restart the operation.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.b31: Current Detection Error 1	The current detection circuit for phase U is faulty.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.b32: Current Detection Error 2	The current detection circuit for phase V is faulty.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.b33: Current Detection Error 3	The detection circuit for the current is faulty.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
	The servomotor main circuit cable is disconnected.	Check for disconnection of the servomotor main circuit cable.	Correct the servomotor wiring.
A.bF0: System Alarm 0	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.bF1: System Alarm 1	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.bF2: System Alarm 2	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.bF3: System Alarm 3	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.bF4: System Alarm 4	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.C10: Servo Overrun Detected (Detected when the servomotor power is ON.)	The order of phases U, V, and W in the servomotor wiring is incorrect.	Check the motor wiring.	Confirm that the servomotor is correctly wired.
	An encoder fault occurred.	—	If the alarm still occurs after turning the power OFF and then ON again, even though the servomotor is correctly wired, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.C80: Absolute Encoder Clear Error and Multi-turn Limit Setting Error	An encoder fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.C90: Encoder Communica- tions Error	Contact fault of connector or incorrect wiring for encoder cable.	Check the connector contact status for encoder cable.	Re-insert the connector and confirm that the encoder is correctly wired.
	Cable disconnection for encoder cable or short-circuit. Or, incorrect cable impedance.	Check the encoder cable.	Use the cable with the specified rating.
	Corrosion caused by improper temperature, humidity, or gas, short-circuit caused by intrusion of water drops or cutting oil, or connector contact fault caused by vibration.	Check the operating environment.	Improve the operating environmental conditions, and replace the cable. If the alarm still occurs, replace the SERVOPACK.
	Malfunction caused by noise interference.	—	Correct the wiring around the encoder by separating the encoder cable from the servomotor main circuit cable or by checking the grounding and other wiring.
	A SERVOPACK fault occurred.	—	Connect the servomotor to another SERVOPACK, and turn ON the control power. If no alarm occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.C91: Encoder Communica- tions Position Data Er- ror	Noise interference occurred on the I/O signal line because the encoder cable is bent and the sheath is damaged.	Check the encoder cable and connector.	Confirm that there is no problem with the cable layout.
	The encoder cable is bundled with a high-current line or near a high-current line.	Check the cable layout for encoder cable.	Confirm that there is no surge voltage on the cable.
	The FG potential varies because of influence from machines on the servomotor side, such as the welder.	Check the cable layout for encoder cable.	Properly ground the machines to separate from the encoder FG.
A.C92: Encoder Communica- tions Timer Error	Noise interference occurred on the I/O signal line from the encoder.	—	Take countermeasures against noise for the encoder wiring.
	Excessive vibration and shocks were applied to the encoder.	Check the operating environment.	Reduce the machine vibration or correctly install the servomotor.
	An encoder fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.CA0: Encoder Parameter Error	An encoder fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.Cb0: Encoder Echoback Error	The wiring and contact for encoder cable are incorrect.	Check the wiring.	Correct the wiring.
	Noise interference occurred due to incorrect cable specifications of encoder cable.	–	Use tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of at least 0.12 mm ² .
	Noise interference occurred because the wiring distance for the encoder cable is too long.	–	The wiring distance must be 50 m max.
	The FG potential varies because of influence from machines on the servomotor side, such as the welder.	Check the cable layout for encoder cable.	Properly ground the machines to separate from encoder FG.
	Excessive vibration and shocks were applied to the encoder.	Check the operating environment.	Reduce the machine vibration or correctly install the servomotor.
	An encoder fault occurred.	–	Turn the power supply OFF and then ON again. If the alarm still occurs, the servomotor may be faulty. Replace the servomotor.
	A SERVOPACK fault occurred.	–	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.CC0: Multiturn Limit Disagreement	When using a direct drive (DD) servomotor, the multiturn limit value (Pn205) is different from that of the encoder.	Check the value of the Pn205.	Correct the setting of Pn205 (0 to 65535).
	The multiturn limit value of the encoder is different from that of the SERVOPACK. Or, the multiturn limit value of the SERVOPACK has been changed.	Check the value of the Pn205 of the SERVOPACK.	Execute Fn013 at the occurrence of alarm.
	A SERVOPACK fault occurred.	–	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.CF1: Feedback Option Module Communications Error (Reception error)	Wiring of cable between serial converter unit and SERVOPACK is incorrect or contact is faulty.	Check the external encoder wiring.	Correct the cable wiring.
	The specified cable is not used between serial converter unit and SERVOPACK.	Confirm the external encoder wiring specifications.	Use the specified cable.
	Cable between serial converter unit and SERVOPACK is too long.	Measure the length of this cable.	Use 20-m cable max.
	Sheath of cable between serial converter unit and SERVOPACK is broken.	Check the cable for damage.	Replace the cable.
A.CF2: Feedback Option Module Communications Error (Timer stop)	Noise interferes with the cable between serial converter unit and SERVOPACK.	–	Correct the wiring around serial converter unit, e.g., separating I/O signal line from main circuit cable or grounding.
	A serial converter unit fault occurred.	–	Replace the serial converter unit.
	A SERVOPACK fault occurred.	–	Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.d00: Position Error Overflow (Position error exceeded the value set in the excessive position error alarm level (Pn520).)	The servomotor U, V, and W wirings is faulty.	Check the servomotor main circuit cable connection.	Confirm that there is no contact fault in the motor wiring or encoder wiring.
	The frequency of the position reference pulse is too high.	Reduce the reference pulse frequency, and operate the SERVOPACK.	Reduce the position reference pulse frequency or acceleration of position reference. Or, reconsider the electronic gear ratio.
	The acceleration of the position reference is too high.	Reduce the reference acceleration, and operate the SERVOPACK.	Apply the smoothing function, such as using position reference acceleration/deceleration time constant (Pn216).
	Setting of the excessive position error alarm level (Pn520) is low against the operating condition.	Check the alarm level (Pn520) to see if it is set to an appropriate value.	Set the Pn520 to proper value.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.d01: Position Error Overflow Alarm at Servo ON	This alarm occurs if the servomotor power is turned ON when the position error is greater than the set value of Pn526 while the servomotor power is OFF.	Check the position error amount (Un008) while the servomotor power is OFF.	Set position error to be cleared while the servomotor power is OFF. Or, correct the excessive position error alarm level at servo ON (Pn526).
A.d02: Position Error Overflow Alarm by Speed Limit at Servo ON	When the position errors remain in the error counter, Pn529 limits the speed if the servomotor power is ON. If Pn529 limits the speed in such a state, this alarm occurs when reference pulses are input and the number of position errors exceeds the value set for the excessive position error alarm level (Pn520).	—	Set position error to be cleared while the servomotor power is OFF. Or, correct the excessive position error alarm level (Pn520). Or, adjust the speed limit level at servo ON (Pn529).
A.d10: Motor-load Position Error Overflow	Motor rotation direction and external encoder installation direction are opposite.	Check the servomotor rotation direction and the external encoder installation direction.	Install the external encoder in the opposite direction, or change the setting of the external encoder usage method (Pn002.3) to reverse the direction.
	Mounting of the load (e.g., stage) and external encoder joint installation are incorrect.	Check the external encoder mechanical connection.	Check the mechanical joints.
A.E71: Safety Option Module Detection Failure	The connection between the SERVOPACK and the safety option module is faulty.	Check the connection between the SERVOPACK and the safety option module.	Correctly connect the safety option module.
	The safety option module was disconnected.	—	Execute Fn014 (Resetting configuration error of option module) with using the digital operator or SigmaWin+ and turn the power supply OFF and then ON again.
	A safety option module fault occurred.	—	Replace the safety option module.
	A SERVOPACK fault occurred.	—	Replace the SERVOPACK.

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Alarm Number: Alarm Name (Alarm Description)	Cause	Investigative Actions	Corrective Actions
A.E72: Feedback Option Module Detection Failure	The connection between the SERVOPACK and the Feedback Option Module is Faulty.	Check the connection between the SERVOPACK and the Feedback Option Module.	Correctly connect the Feedback Option Module.
	The Feedback Option Module was disconnected.	—	Execute resetting configuration error in option modules (Fn014) and turn the power supply OFF and then ON again.
	A Feedback Option Module fault occurred.	—	Replace the Feedback Option Module.
	A SERVOPACK fault occurred.	—	Replace the SERVOPACK.
A.E74: Unsupported Safety Option Module	A safety option module fault occurred.	—	Replace the safety option module.
	A unsupported safety option module was connected.	Refer to the catalog of the connected safety option module.	Connect a compatible safety option module.
A.E75: Unsupported Feed- back Option Module	A feedback option module fault occurred.	—	Replace the feedback option module.
	A unsupported feedback option module was connected.	Refer to the catalog of the connected feedback option module or the manual of the SERVOPACK.	Connect a compatible feedback option module.
A.Eb1: Safety Function Signal Input Timing Error	The lag between activations of the input signals /HWBB1 and /HWBB2 for the HWBB function is ten second or more.	Measure the time lag between the /HWBB1 and /HWBB2 signals.	The output signal circuits or devices for /HWBB1 and /HWBB2 or the SERVOPACK input signal circuits may be faulty. Alternatively, the input signal cables may be disconnected. Check if any of these items are faulty or have been disconnected.
A.F10: Main Circuit Cable Open Phase (With the main power supply ON, voltage was low for more than 1 second in an R, S, or T phase.) (Detected when the main power supply was turned ON.)	The three-phase power supply wiring is incorrect.	Check the power supply wiring.	Confirm that the power supply is correctly wired.
	The three-phase power supply is unbalanced.	Measure the voltage at each phase of the three-phase power supply.	Balance the power supply by changing phases.
	A single-phase power is input without setting Pn00B.2 (power supply method for three-phase SERVOPACK) to 1 (single-phase power supply).	Check the power supply and the parameter setting.	Match the parameter setting to the power supply.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
FL-1*2: System Alarm	SERVOPACK failure	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
FL-2*2: System Alarm		—	
CPF00: Digital Operator Transmission Error 1	The contact between the digital operator and the SERVOPACK is faulty.	Check the connector contact.	Insert securely the connector or replace the cable.
	Malfunction caused by noise interference.	—	Keep the digital operator or the cable away from noise sources.
CPF01: Digital Operator Transmission Error 2	A digital operator fault occurred.	—	Disconnect the digital operator and then re-connect it. If the alarm still occurs, the digital operator may be faulty. Replace the digital operator.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.

*2. These alarms are not stored in the alarm history and are displayed only in the panel display.

10.2 Warning Displays

The following sections describe troubleshooting in response to warning displays.

The warning name, warning meaning, and warning code output are listed in order of the warning numbers in *10.2.1 List of Warnings*.

The causes of warnings and troubleshooting methods are provided in *10.2.2 Troubleshooting of Warnings*.

10.2.1 List of Warnings

This section provides list of warnings.

Warning Number	Warning Name	Meaning	Warning Code Output		
			ALO1	ALO2	ALO3
A.900	Position Error Overflow	Position error exceeded the parameter setting (Pn520×Pn51E/100).	H	H	H
A.901	Position Error Overflow Alarm at Servo ON	When the servomotor power is ON, the position error exceeded the parameter setting (Pn526×Pn528/100).	H	H	H
A.910	Overload	This warning occurs before the overload alarms (A.710 or A.720) occur. If the warning is ignored and operation continues, an overload alarm may occur.	L	H	H
A.911	Vibration	Abnormal vibration at the motor speed was detected. The detection level is the same as A.520. Set whether to output an alarm or warning by the vibration detection switch (Pn310).	L	H	H
A.920	Regenerative Overload	This warning occurs before the regenerative overload alarm (A.320) occurs. If the warning is ignored and operation continues, a regenerative overload alarm may occur.	H	L	H
A.921	Dynamic Brake Overload	This warning occurs before dynamic brake overload alarm (A.731) occurs. If the warning is ignored and operation continues, a dynamic brake overload alarm may occur.	H	L	H
A.930	Absolute Encoder Battery Error	This warning occurs when the voltage of absolute encoder's battery is lowered.	L	L	H
A.941	Change of Parameters Requires Restart	Parameters that require the restart have been changed.	H	H	L
A.971	Undervoltage	This warning occurs before undervoltage alarm (A.410) occurs. If the warning is ignored and operation continues, an undervoltage alarm may occur.	L	L	L
A.9A0	Overtravel	Overtravel is detected while the servomotor power is ON.	H	L	L

Note 1. Warning code is not output without setting Pn001.3 = 1 (outputs both alarm codes and warning codes).

2. If Pn008.2 = 1 (does not detect warning) is selected, no warnings will be detected except for an undervoltage warning (A.971).

10.2.2 Troubleshooting of Warnings

Refer to the following table to identify the cause of a warning and the action to be taken. Contact your Yaskawa representative if the problem cannot be solved by the described corrective action.

Warning Number: Warning Name (Warning Description)	Cause	Investigative Actions	Corrective Actions
A.900: Position Error Overflow	The servomotor U, V, and W wirings is faulty.	Check the servomotor main circuit cable connection.	Confirm that there is no contact fault in the motor wiring or encoder wiring.
	The SERVOPACK gain is too low.	Check the SERVOPACK gain.	Increase the servo gain by using the function such as advanced autotuning.
	The frequency of the position reference pulse is too high.	Reduce the reference pulse frequency, and operate the SERVOPACK.	Reduce the position reference pulse frequency or acceleration of position reference. Or, reconsider the electronic gear ratio.
	The acceleration of the position reference is too high.	Reduce the reference acceleration, and operate the SERVOPACK.	Apply the smoothing function, such as using the position reference acceleration/deceleration time constant (Pn216).
	Setting of the excessive position error alarm level (Pn520) is low against the operating condition.	Check the alarm level (Pn520) to see if it is set to an appropriate value.	Set the Pn520 to proper value.
	A SERVOPACK fault occurred.	—	Turn the power supply OFF and then ON again. If the alarm still occurs, the SERVOPACK may be faulty. Replace the SERVOPACK.
A.901: Position Error Overflow Alarm at Servo ON	When the servomotor power is ON, the position error exceeded the parameter setting (Pn526×Pn528/100).	—	Set Pn200.2 to 0 to clear the number of position error while the servomotor power is OFF. Or set an appropriate value for the excessive position error warning level at servo ON (Pn528).
A.910: Overload (Warning before alarm A.710 or A.720 occurs)	Incorrect wiring or contact fault of servomotor and encoder.	Check the wiring.	Confirm that the servomotor and encoder are correctly wired.
	Operation beyond the overload protection characteristics.	Check the motor overload characteristics and executed run command.	Reconsider the load conditions and operating conditions. Or, increase the motor capacity.
	Excessive load was applied during operation because the servomotor was not driven due to mechanical problems.	Check the executed operation reference and motor speed.	Remove the mechanical problems.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.

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Warning Number: Warning Name (Warning Description)	Cause	Investigative Actions	Corrective Actions
A.911: Vibration	Abnormal vibration was detected at the motor speed.	Check for abnormal noise from the servomotor, and check the speed and torque waveforms during operation.	Reduce the motor speed or reduce the servo gain by using the function such as one-parameter tuning.
	The moment of inertia ratio (Pn103) value is greater than the actual value or is greatly changed.	Check the moment of inertia ratio.	Set the moment of inertia ratio (Pn103) to an appropriate value.
A.920: Regenerative Overload (Warning before the alarm A.320 occurs)	The power supply voltage exceeds the specified limit.	Measure the power supply voltage.	Set the power supply voltage within the specified range.
	Insufficient external regenerative resistance, regenerative resistor capacity, or SERVOPACK capacity. Or, regenerative power has been continuously flowing back.	Check the operating condition or the capacity using the capacity selection Software SigmaJunmaSize+, etc.	Change the regenerative resistance, regenerative resistor capacity, or SERVOPACK capacity. Reconsider the operating conditions using the capacity selection software SigmaJunmaSize+, etc.
	Regenerative power continuously flowed back because negative load was continuously applied.	Check the load to the servomotor during operation.	Reconsider the system including servo drives, machine, and operating conditions.
A.921: Dynamic Brake Overload (Warning before the alarm A.731 occurs)	The servomotor rotates because of external force.	Check the operation status.	Take measures to ensure the servomotor will not rotate because of external force.
	The rotating energy at a DB stop exceeds the DB resistance capacity.	Check the power consumed by DB resistance (Un00B) to see how many times the DB has been used.	Reconsider the following: <ul style="list-style-type: none"> • Reduce the motor reference speed. • Reduce the moment of inertia ratio. • Reduce the number of times of the DB stop operation.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.930: Absolute Encoder Battery Error (The absolute encoder battery voltage is lower than the specified value.) * Only when an absolute encoder is connected.	The battery connection is incorrect.	Check the battery connection.	Reconnect the battery.
	The battery voltage is lower than the specified value 2.7 V.	Measure the battery voltage.	Replace the battery.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.941: Change of Parameters Requires Restart	Parameters that require the restart have been changed.	—	Turn OFF the power and ON again.

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Warning Number: Warning Name (Warning Description)	Cause	Investigative Actions	Corrective Actions
A.971: Under-voltage	<ul style="list-style-type: none"> • For 100 VAC SERVOPACKs: The AC power supply voltage is 60 V or less. • For 200-VAC SERVOPACKs: The AC power supply voltage is 140 V or less. • For 400-VAC SERVOPACKs: The AC power supply voltage is 280 V or less. 	Measure the power supply voltage.	Set the power supply voltage within the specified range.
	The power supply voltage dropped during operation.	Measure the power supply voltage.	Increase the power supply capacity.
	Occurrence of instantaneous power interruption.	Measure the power supply voltage.	When the instantaneous power cut hold time (Pn509) is set, decrease the setting.
	The SERVOPACK fuse is blown out.	—	Replace the SERVOPACK and connect a reactor to the SERVOPACK.
	A SERVOPACK fault occurred.	—	The SERVOPACK may be faulty. Replace the SERVOPACK.
A.9A0: Overtravel (Overtravel status is detected.)	When the servomotor power is ON, overtravel status is detected.	Check the input signal monitor (Un005) to check the status of the overtravel signals.	<p>Refer to <i>10.3 Troubleshooting Malfunction Based on Operation and Conditions of the Servomotor</i>. Even if overtravel signals were not shown by the input signal monitor (Un005), momentary overtravel may have been detected. Take the following precautions.</p> <ul style="list-style-type: none"> • Do not specify movements that would cause overtravel from the host controller. • Check the wiring of the overtravel signals. • Take countermeasures for noise.

10.3 Troubleshooting Malfunction Based on Operation and Conditions of the Servomotor

Troubleshooting for the malfunctions based on the operation and conditions of the servomotor is provided in this section.

Be sure to turn OFF the servo system before troubleshooting items shown in bold lines in the table.

Problem	Probable Cause	Investigative Actions	Corrective Actions
Servomotor Does Not Start	The control power supply is not ON.	Check voltage between control power terminals.	Correct the wiring.
	The main circuit power supply is not ON.	Check the voltage between main circuit power terminals.	Correct the wiring.
	Wiring of I/O signal connector CN1 is faulty or disconnected.	Check if the connector CN1 is properly inserted and connected.	Correct the connector CN1 connection.
	Wiring for servomotor main circuit cable or encoder cable is disconnected.	Check the wiring.	Correct the wiring.
	Overloaded	Run under no load and check the load status.	Reduce load or replace with larger capacity servomotor.
	Encoder type differs from parameter setting (Pn002.2).	Check the settings for parameter Pn002.2.	Set parameter Pn002.2 to the encoder type being used.
	Speed/position references not input	Check the allocation status of the input signals.	Allocate input signals so that the speed/position reference is input correctly.
	Settings for the input signal selections (Pn50A to Pn50D) is incorrect.	Check the settings for parameters Pn50A to Pn50D.	Correct the settings for parameter Pn50A to Pn50D.
	Servo ON signal (/S-ON) stays OFF.	Check the settings for parameters Pn50A.0 and Pn50A.1.	Set the parameters Pn50A.0 and Pn50A.1 to turn the /S-ON signal ON.
	/P-CON input function setting is incorrect.	Check the settings for parameter Pn000.1.	Set parameters to match the application.
	SEN input is OFF.	Check the ON/OFF status of the SEN input.	If using an absolute encoder, turn the SEN input signal ON.
	Reference pulse mode selection is incorrect.	Check the Pn200.0 setting and the reference pulse form.	Match the Pn200.0 setting and the reference pulse form.
	Speed control: Speed reference input is incorrect.	Check V-REF and SG to confirm if the control method and the input are agreed.	Correct the control method selection parameter, and the input signal.
	Torque control: Torque reference input is incorrect.	Check V-REF and SG to confirm if the control method and the input are agreed.	Correct the control method selection parameter, and the input signal.
	Position control: Reference pulse input is incorrect.	Check Pn200.0 reference pulse form and sign + pulse signal.	Correct the control method selection parameter, and the input signal.
	Position error clear (/CLR) input has not been turned OFF.	Check /CLR input signals (CN1-14 and -15).	Turn /CLR input signals OFF.
	The forward run prohibited (P-OT) and reverse run prohibited (N-OT) input signals are turned OFF.	Check P-OT or N-OT input signal.	Turn P-OT or N-OT input signal ON.
	The safety input signal (/HWBB1 or /HWBB2) remains OFF.	Check the /HWBB1 and /HWBB2 input signal.	Set the /HWBB1 and /HWBB2 input signal to ON. When not using the safety function, mount the safety function jumper connector (provided as an accessory) on the CN8.
	A SERVOPACK fault occurred.	—	Replace the SERVOPACK.

(cont'd)

Problem	Probable Cause	Investigative Actions	Corrective Actions
Servomotor Moves Instantaneously, and then Stops	Servomotor wiring is incorrect.	Check the wiring.	Correct the wiring.
	Encoder wiring is incorrect.	Check the wiring.	Correct the wiring.
Servomotor Speed Unstable	Wiring connection to servomotor is defective.	Check connections of power line (phases U, V, and W) and encoder connectors.	Tighten any loose terminals or connectors and correct the wiring.
Servomotor Rotates Without Reference Input	Speed control: Speed reference input is incorrect.	Check V-REF and SG to confirm if the control method and the input are agreed.	Correct the control method selection parameter, and the input signal.
	Torque control: Torque reference input is incorrect.	Check V-REF and SG to confirm if the control method and the input are agreed.	Correct the control method selection parameter, and the input signal.
	Speed reference offset is incorrect.	The SERVOPACK offset is adjusted incorrectly.	Adjust the SERVOPACK offset.
	Position control: Reference pulse input is incorrect.	Check the reference pulse form (Pn200.0) and sign + pulse signal.	Correct the control method selection parameter, and the input signal.
	A SERVOPACK fault occurred.	–	Replace the SERVOPACK.
Dynamic Brake Does Not Operate	Improper Pn001.0 setting	Check the setting for parameter Pn001.0.	Correct the setting for parameter Pn001.0.
	DB resistor disconnected	Check if excessive moment of inertia, motor overspeed, or DB frequently activated occurred.	Replace the SERVOPACK, and reduce the load.
	DB drive circuit fault	–	There is a defective component in the DB circuit. Replace the SERVOPACK.
Abnormal Noise from Servomotor	The servomotor largely vibrated during execution of tuning-less function.	Check the motor speed waveform.	Reduce the load so that the moment of inertia ratio becomes within the allowable value, or increase the load level or lower the tuning level for the tuning-less levels setting (Fn200).
	Mounting is not secured.	Check if there are any loose mounting screws.	Tighten the mounting screws.
		Check if there is misalignment of couplings.	Align the couplings.
		Check if there are unbalanced couplings.	Balance the couplings.
	Bearings are defective.	Check for noise and vibration around the bearings.	Replace the servomotor.
	Vibration source at the driven machine.	Check for any foreign matter, damage, or deformations on the machinery's movable parts.	Contact the machine manufacturer.
	Noise interference due to incorrect I/O signal cable specifications.	The I/O signal cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use the specified I/O signal cable.
	Noise interference due to length of I/O signal cable.	Check the length of the I/O signal cable.	The I/O signal cable length must be no more than 3 m.
	Noise interference due to incorrect cable specifications of encoder cable.	The encoder cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use the specified encoder cable.
Noise interference due to length of encoder cable.	Check the length of the encoder cable.	The encoder cable must be no more than 50 m.	

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Problem	Probable Cause	Investigative Actions	Corrective Actions
Abnormal Noise from Servomotor (cont'd)	Noise interference due to damaged encoder cable.	Check if the encoder cable is bent and the sheath is damaged.	Replace the encoder cable and correct the cable layout.
	Excessive noise to the encoder cable.	Check if the encoder cable is bundled with a high-current line or near a high-current line.	Correct the cable layout so that no surge is applied.
	The FG potential varies because of influence from machines on the servomotor side, such as the welder.	Check if the machines are correctly grounded.	Properly ground the machines to separate from the encoder FG.
	SERVOPACK pulse counting error due to noise interference	Check if there is noise interference on the I/O signal line from the encoder.	Take measures against noise in the encoder wiring.
	Excessive vibration and shock to the encoder	Check if vibration from the machine occurred or servomotor installation is incorrect (mounting surface accuracy, fixing, alignment, etc.).	Reduce vibration from the machine, or secure the servomotor installation.
	An encoder fault occurred.	–	Replace the servomotor.
Servomotor Vibrates at Frequency of Approx. 200 to 400 Hz.	Unbalanced servo gains	Check to see if the servo gains have been correctly adjusted.	Execute the advanced autotuning.
	Speed loop gain value (Pn100) too high.	Check the speed loop gain (Pn100). Factory setting: $K_v = 40.0$ Hz	Reduce the speed loop gain (Pn100).
	Position loop gain value (Pn102) too high.	Check the position loop gain (Pn102). Factory setting: $K_p = 40.0/s$	Reduce the position loop gain (Pn102).
	Incorrect speed loop integral time constant (Pn101)	Check the speed loop integral time constant (Pn101). Factory setting: $T_i = 20.0$ ms	Correct the speed loop integral time constant (Pn101).
	Incorrect moment of inertia ratio (Pn103)	Check the moment of inertia ratio (Pn103).	Correct the moment of inertia ratio (Pn103).
High Motor Speed Overshoot on Starting and Stopping	Unbalanced servo gains	Check to see if the servo gains have been correctly adjusted.	Execute the advanced autotuning.
	Speed loop gain value (Pn100) too high	Check the speed loop gain (Pn100). Factory setting: $K_v = 40.0$ Hz	Reduce the speed loop gain (Pn100).
	Position loop gain value (Pn102) too high	Check the position loop gain (Pn102). Factory setting: $K_p = 40.0/s$	Reduce the position loop gain (Pn102).
	Incorrect speed loop integral time constant (Pn101)	Check the speed loop integral time constant (Pn101). Factory setting: $T_i = 20.0$ ms	Correct the speed loop integral time constant (Pn101).
	Incorrect moment of inertia ratio data (Pn103)	Check the moment of inertia ratio (Pn103).	Correct the moment of inertia ratio (Pn103).

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Problem	Probable Cause	Investigative Actions	Corrective Actions
Absolute Encoder Position Difference Error (The position saved in the host controller when the power was turned OFF is different from the position when the power was next turned ON.)	Noise interference due to incorrect cable specifications of encoder cable.	The encoder cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use the specified encoder cable.
	Noise interference due to length of encoder cable.	Check the length of the encoder cable.	The encoder cable must be no more than 50 m.
	Noise interference due to damaged encoder cable.	Check if the encoder cable is bent and the sheath is damaged.	Replace the encoder cable and correct the cable layout.
	Excessive noise to the encoder cable.	Check if the encoder cable is bundled with a high-current line or near a high-current line.	Correct the cable layout so that no surge is applied.
	FG potential varies because of influence of machines such as welders at the servomotor.	Check if the machines are correctly grounded.	Ground machines correctly, and prevent diversion to the FG on the encoder side.
	SERVOPACK pulse counting error due to noise interference	Check if there is noise interference on the I/O signal line from the encoder.	Take measures against noise in the encoder wiring.
	Excessive vibration and shock to the encoder	Check if vibration from the machine occurred or servomotor installation is incorrect (mounting surface accuracy, fixing, alignment, etc.).	Reduce vibration from the machine, or secure the servomotor installation.
	An encoder fault occurred.	–	Replace the servomotor.
	A SERVOPACK fault occurred. (The pulse count does not change.)	–	Replace the SERVOPACK.
	Host controller multiturn data reading error	Check the error detection section of the host controller.	Correct the error detection section of the host controller.
Check if the host controller is executing data parity checks.		Execute a multiturn data parity check.	
Check noise in the cable between the SERVOPACK and the host controller.		Take measures against noise, and again execute a multiturn data parity check.	
Overtravel (OT)	Forward or reverse run prohibited signal is input.	Check the external power supply (+24 V) voltage for the input signal.	Correct the external power supply (+24 V) voltage.
		Check if the overtravel limit switch operates properly.	Correct the overtravel limit switch.
		Check if the overtravel limit switch is wired correctly.	Correct the overtravel limit switch wiring.
		Check the settings for parameters Pn50A and Pn50B.	Correct the settings for parameters Pn50A and Pn50B.
	Forward or reverse run prohibited signal malfunctioning.	Check the fluctuation of the external power supply (+24 V) voltage for the input signal.	Stabilize the external power supply (+24 V) voltage.
		Check if the overtravel limit switch operates correctly.	Correct the overtravel limit switch.
		Check if the overtravel limit switch wiring is correct. (check for damaged cables or loose screws.)	Correct the overtravel limit switch wiring.
	Incorrect forward or reverse run prohibited signal (P-OT/N-OT) allocation (parameters Pn50A.3, Pn50B.0)	Check if the P-OT signal is allocated in Pn50A.3.	If another signal is allocated in Pn50A.3, allocate P-OT.
		Check if the N-OT signal is allocated in Pn50B.0.	If another signal is allocated in Pn50B.0, allocate N-OT.
	Incorrect servomotor stop method selection	Check the settings for parameters Pn001.0 and Pn001.1 when the servomotor power is OFF.	Select a servomotor stop method other than "coast to stop."
Check the settings for parameters Pn001.0 and Pn001.1 when in torque control.		Select a servomotor stop method other than "coast to stop."	

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Problem	Probable Cause	Investigative Actions	Corrective Actions
Improper Stop Position by Overtravel (OT) Signal	Improper limit switch position and dog length	–	Install the limit switch at the appropriate position.
	The overtravel limit switch position is too short for the coasting distance.	–	Install the overtravel limit switch at the appropriate position.
Position Error (Without Alarm)	Noise interference due to incorrect encoder cable specifications	The encoder cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use the specified encoder cable.
	Noise interference due to length of encoder cable.	Check the length of the encoder cable.	The encoder cable must be no more than 50 m.
	Noise influence due to damaged encoder cable.	Check if the encoder cable is bent and the sheath is damaged.	Replace the encoder cable and modify the cable layout.
	Excessive noise to encoder cable.	Check if the encoder cable is bundled with a high-current line or near a high-current line.	Change the cable layout so that no surge is applied.
	The FG potential varies because of influence from machines on the servomotor side such as the welder.	Check if the machines are correctly grounded.	Properly ground the machines encoder FG.
	SERVOPACK pulse count error due to noise	Check if the I/O signal line from the encoder is influenced by noise.	Take measures against noise in the encoder wiring.
	Excessive vibration and shock to the encoder	Check if vibration from the machine occurred or servomotor installation is incorrect (mounting surface accuracy, fixing, alignment, etc.).	Reduce the machine vibration or mount the servomotor securely.
	Unsecured coupling between machine and servomotor	Check if a position error occurs at the coupling between machine and servomotor.	Secure the coupling between the machine and servomotor.
	Noise interference due to improper I/O signal cable specifications	The I/O signal cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use input signal cable with the specified specifications.
	If the reference pulse input multiplication switching function is being used, noise may be causing the I/O signals (/PSEL and /PSELA) used for this function to be falsely detected.	The I/O signal cable must be tinned annealed copper shielded twisted-pair or screened unshielded twisted-pair cable with a core of 0.12 mm ² min.	Use input signal cable that satisfy specifications.
	Noise interference due to length of I/O signal cable	Check the I/O signal cable length.	The I/O signal cable length must be no more than 3 m.
	An encoder fault occurred. (The pulse count does not change.)	–	Replace the servomotor.
	A SERVOPACK fault occurred.	–	Replace the SERVOPACK.
Servomotor Overheated	Ambient operating temperature too high	Measure the servomotor ambient operating temperature.	Reduce the ambient operating temperature to 40°C or less.
	Servomotor surface dirty	Visually check the surface.	Clean dust and oil from the surface.
	Servomotor overloaded	Check the load status with monitor.	If overloaded, reduce load or replace with larger capacity SERVOPACK and servomotor.