

形式一覧表
Type List

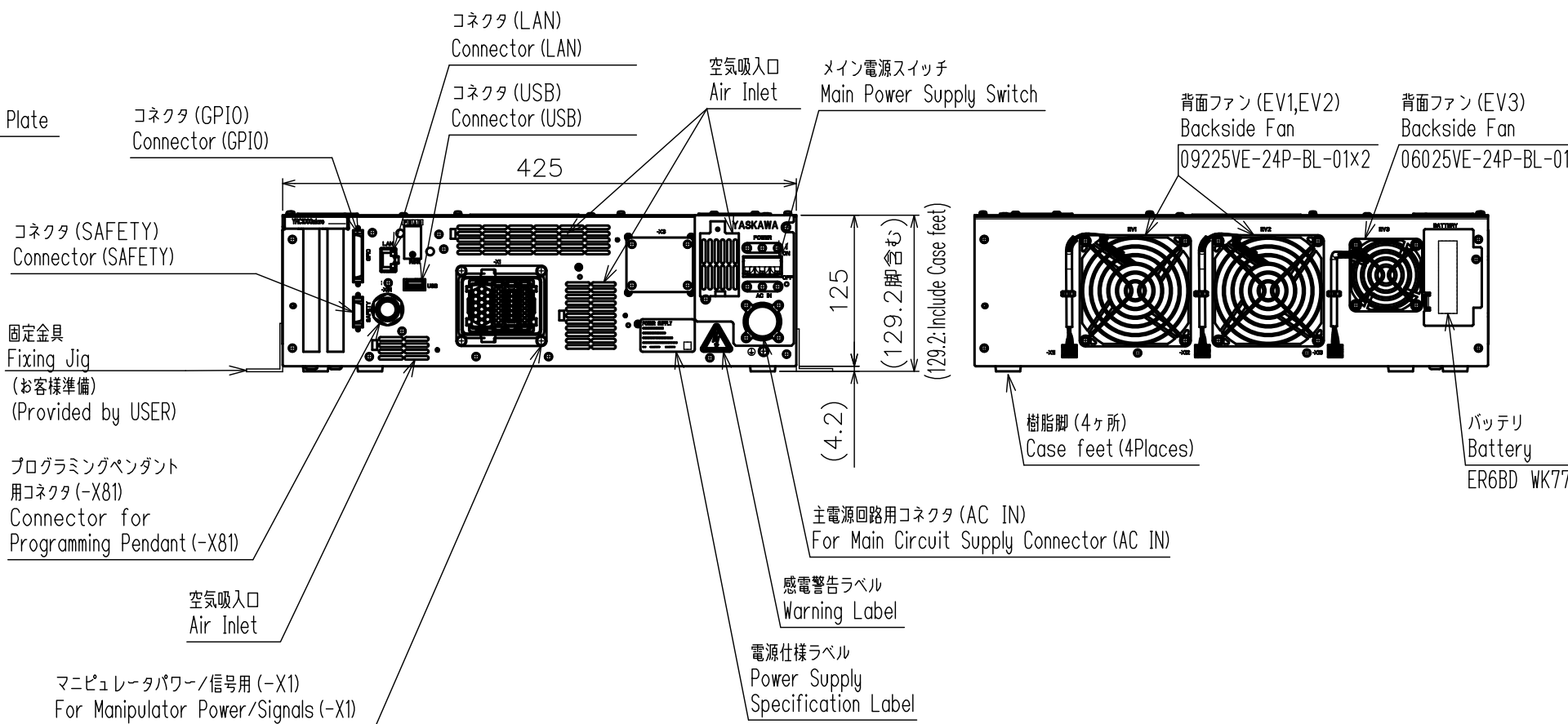
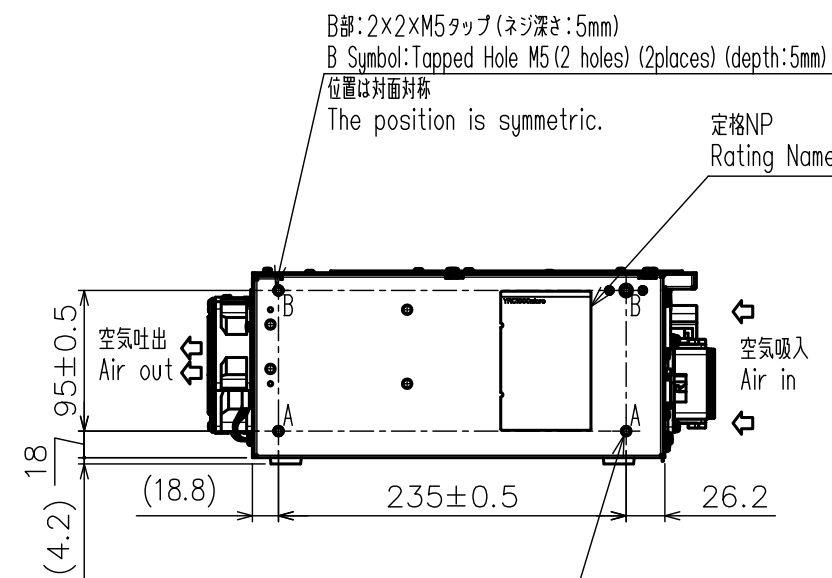
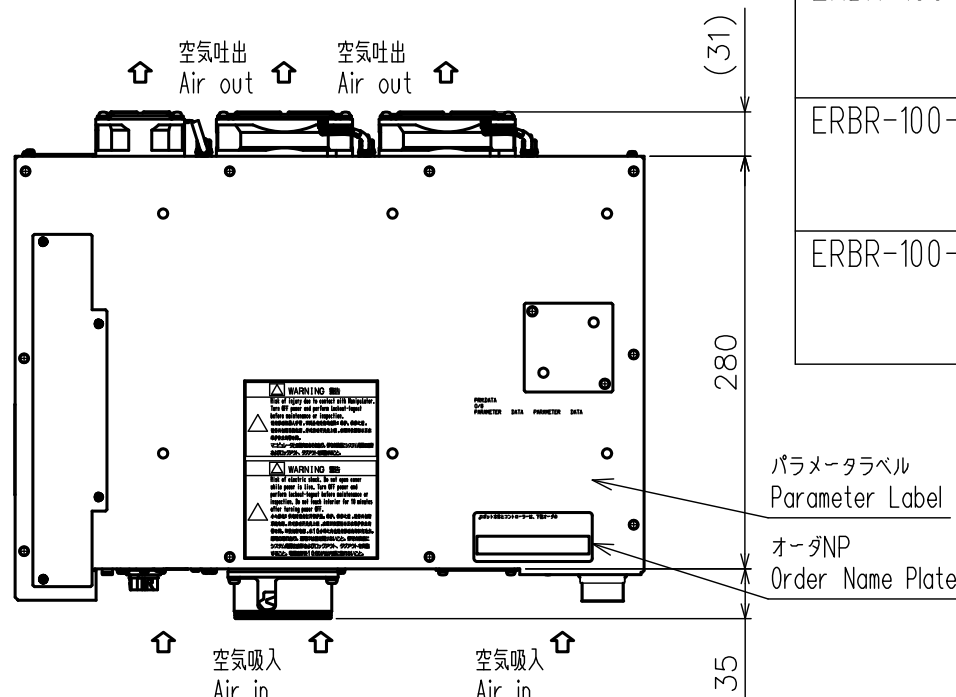
盤形式 Controller Type	ロボット機種 Robot Type	備考 Remark
ERBR-100-06VX8-A00	GP8 GP7	国内・アジア・北米 For Japan/Asia /North America
ERBR-100-06VX05-A00	MotoMINI	国内・アジア・北米 For Japan/Asia /North America
ERBR-100-06VXH12-A00	GP12	国内・アジア・北米 For Japan/Asia /North America

注記

- 制御盤の冷却及びメンテナンスの為、設置スペース図記載の寸法を確保してください。
- 床置きの場合は、A穴(4ヶ所)を使用し、盤固定金具を取付け、アンカボルトにて地面に固定してください。
尚、盤固定金具は、お客様にてご準備ください。
ラック固定時はA穴・B穴(8ヶ所)を使用し確実に固定してください。

Notes

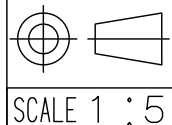
- Secure the dimensions stated in the placement space chart for cooling and maintenance.
- Use four holes marked with the symbol "A" to fix the controller on the floor with fixing jigs and anchor bolts.
When fixing the rack, Use A and B hole (8 places).



- 注2)
See Notes (2)
2×2×M5タップ(ネジ深さ:5mm)
Tapped Hole M5 (2 holes) (2places) (depth:5mm)
A部(制御盤固定用/固定金具取付用穴)
A Symbol (For Fixing)
固定金具取付穴位置は対称
The position for fix is symmetric.

Note:
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3.No warranty is given in relation to the data including the specification.
4.We are not responsible for any damages or loss caused by the use of the data.

FOR STUDY PURPOSE ONLY



Reference Drawing

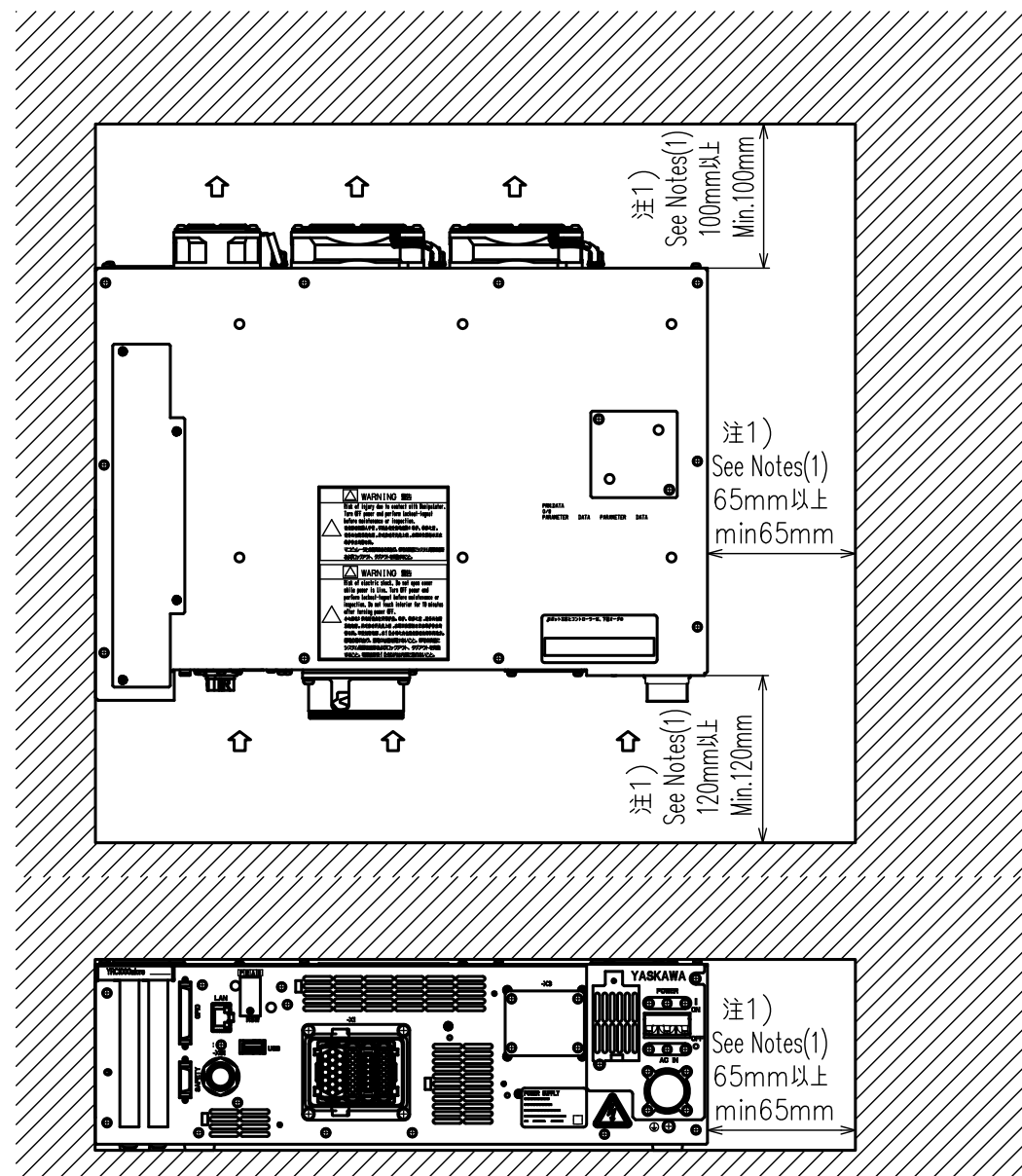
TITLE YRC1000 micro
Dimension Diagram

DRWN DATE '17.04.10

DWG.NO. HB1380431 1/2

SIZE A3

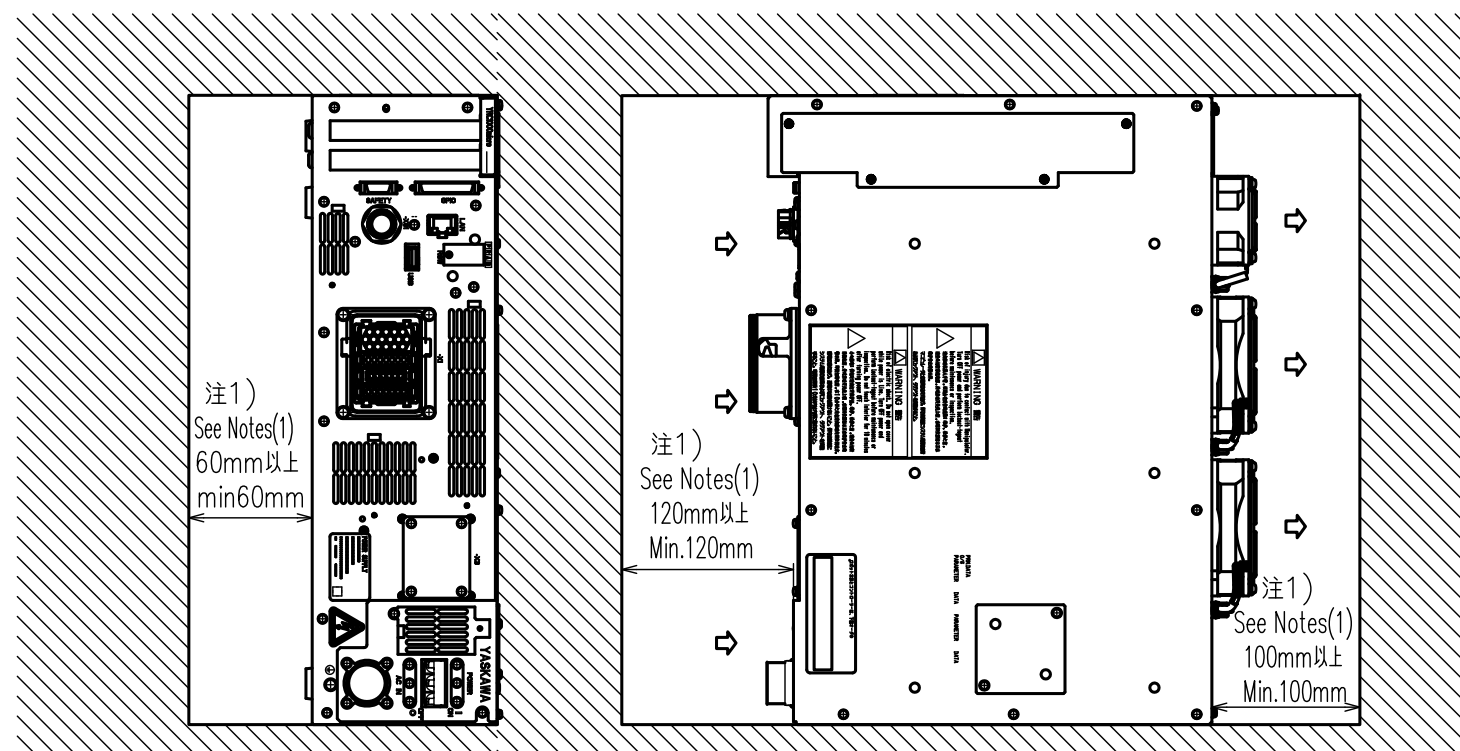
設置スペース図
Installation space



横置きの場合
Horizontally mounted

コネクター一覧表
Connector List

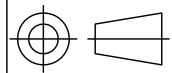
器具符号 Devise Symbol	コネクタ形式 Connector Type	備考 Remark
AC IN	CE05-2A18-10PD (DDK)	主電源回路用 For Main Power Supply
-X1	KN01AM-SHL-A (JAE)	マニピュレータ用 (パワー/信号用) For Manipulator (Power/Signals)
USB	292336-1 (TE)	USB用 For USB
LAN	26-51024KB13-1 (UDE)	LAN用 For LAN
-X81	CM09Y-R25S (DDK)	プログラミングペンダント用 For Programming Pendant
GPIO	10250-52A2PL (3M)	入出力用 For General Input and Output
SAFETY	10220-52A2PL (3M)	安全入出力用 For Safety Input and Output



縦置きの場合
Vertically mounted

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SCALE 1:5

YASKAWA
株式会社 安川電機

Reference Drawing

TITLE YRC1000 micro
Dimension Diagram

DRWN DATE '17.04.10

DWG.NO. HB1380431 3/2

SIZE A3